Introduction to Bayesian inference and its application in medical biology

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DECLARATION OF INTEREST AS PART OF TRAINING MISSIONS MADE FOR THE CNBH

Professor Panagiotis Tsiamyrtzis Working at <u>Politecnico</u> di Milano & Athens University of Economics and Business (Establishment – service) solemnly declare

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The Bayesian versus the Frequentist Approach

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 - we need to elicit it from the data, i.e. collect the data $\{x_1, \ldots, x_n\}$ and derive the distribution, e.g. $X | (\theta_1, \theta_2) \sim N(\theta_1, \theta_2)$.

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- Goodness of fit tests and plots should be used to examine how well an assumed theoretical distribution fits the observed data.

















There are two (mainstream) schools of thought in statistics regarding the way we deal with the unknown parameter θ :

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 - The two schools differ drastically on the way they handle the unknown parameter θ .

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• Example:

In the case of a fair coin toss (la pièce lancée en l'air), the frequentist probability P(H) is 1/2, not because there are two equally likely outcomes (classical interpretation of probability) but because in repeated trials the empirical frequency converges to the limit 1/2 as the number of trials goes to infinity, i.e.

$$P(H) = \frac{\# \text{ of heads}}{\# \text{ of trials}} = \frac{n_H}{n} \stackrel{n \to \infty}{\longrightarrow} \frac{1}{2}$$







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Tosses

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Bayesian SPC/M

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 - **predictions** for future observable(s).

• The frequentist approach attempts to be "**objective**" in setting the probabilities. However, it relies heavily on the assumption that we are capable to repeat an experiment, infinite number of times, under "identical" conditions. The latter is restrictive in several real life applications making it really difficult to provide a frequentist based evaluation. Here are some examples:

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What is the probability that tomorrow noon will rain at Paris?
Frequentist School

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• The lack or repeatability in the previous examples lead to the embarrassing answer that this probability can either be 0 (if the event will not occur) or 1 (if it occurs).

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- Thus inference regarding θ becomes available thanks to long term frequency properties. Precisely, we consider infinite repeated sampling, for **fixed** value of θ.
- While point estimation seems to be well aligned in this school, the assumption of a **fixed** parameter value can cause great difficulty in the interpretation of interval estimates (confidence intervals) and/or hypotheses testing.

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• Example:

In the case of tossing a coin, the subjective probability P(H) = 0.4and P(T) = 0.6 can express one's personal opinion for a specific coin. A different person can come with a different pair of values based on his/her personal information. • In contrast to the frequentist "objective" conjecture in the Bayesian school the probabilities are set **subjectively**, depending on **what bet a person is willing to take** regarding the occurrence of the specific outcome.

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• Conformity to the probability calculus is necessary and sufficient for coherence.

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- So in the Bayesian school the parameter θ is considered to be a random variable.
- Its distribution, will quantify our (**subjective**) opinion regarding θ (before looking the data) with a prior distribution: $\pi(\theta)$.
- Then Bayes theorem will do the magic **updating** the prior distribution to posterior, in the light of the data.

Bayes theorem

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$$p(\theta|\mathbf{x}) = \frac{f(\mathbf{x}|\theta)\pi(\theta)}{\int f(\mathbf{x}|\theta)\pi(\theta)d\theta}$$

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- $\mathbf{x} = \{x_1, \dots, x_n\}$ are the observed data.
- $f(\mathbf{x}|\theta)$ refers to the likelihood of the data
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- So the Bayes theorem is nothing more that an **updating mechanism**, where the prior is updated to posterior in the light of evidence coming from the available data.

The Bayesian approach consists of the following steps:

- (a) Define the likelihood: $f(\mathbf{x}|\theta)$.
- (b) Define the prior distribution: $\pi(\theta)$.
- (c) Compute the posterior distribution: $p(\theta|\mathbf{x})$.
- (d) Decision Making: Draw inference regarding θ (point/interval estimates and hypothesis testing).
- (e) Derive the predictive distribution $f(x_{n+1}|x_1, x_2, ..., x_n)$ of a future observable and make predictions.

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• The prior should reflect our personal (**subjective**) opinion (information) regarding the parameter, **before** we look at the data. The only thing we need to be careful about, is to be coherent, which will happen if we will obey the probability laws.

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Prior Distribution

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- Different priors applied on the same data will lead to different posteriors.
- The last bullet, raised (and keeps raising) the major criticism from non-Bayesians (see for example Efron (1986), "Why isn't everyone a Bayesian"). However, Bayesians love the opportunity to be subjective. Lets see an example:

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Based on the frequentist approach the Maximum Likelihood Estimate of the unknown parameter is $\hat{\theta} = \overline{x} = 1$ in both cases.

Prior Distribution: example

But is this really what we believe?

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If the two probability numbers that you wrote down about θ in the previous setups were not the same number, then you are thinking and acting as **Bayesian** (even though you might not know about it!).

Computing the posterior: example

• Assume that we have a random sample of size *n*: $\mathbf{x} = (x_1, x_2, ..., x_n)$ from the Normal (Gaussian) distribution, i.e.:

$$X_i | heta \sim N\left(heta, \ \sigma^2
ight)$$

with σ^2 being known.

• If the prior distribution of the unknown parameter heta is Normal, i.e. :

$$\pi(heta) \sim \mathsf{N}\left(\mu, au^2
ight)$$

with μ and τ^2 being known.

• Then the posterior distribution of $\theta | \mathbf{x}$ will be given by:

$$heta | \mathbf{x} \sim \mathcal{N}\left(rac{ au^2 \overline{\mathbf{x}} + rac{\sigma^2}{n} \mu}{rac{\sigma^2}{n} + au^2}, \ rac{rac{\sigma^2}{n} au^2}{rac{\sigma^2}{n} + au^2}
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We will use the posterior distribution of $\theta | \mathbf{x}$ derived in the last example:

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Let's look on some graphical illustrations regarding the effect of the sample size *n* and the variance of the prior distribution, τ^2 . Specifically, let's assume that $\overline{x} = 4$ and:

- n = 1, 10, 100 with $\pi(\theta) \sim N(0, 1)$
- n = 1 with $\pi(\theta) \sim N(0, 10^2)$

• n = 1, 10, 100 with $\pi(\theta) \sim N(0, 0.1^2)$

Plot of the N(0, 1) prior distribution:

Normal prior



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Plot of $p(\theta|x)$, when n = 1 with $\pi(\theta) \sim N(0, 1)$:

Normal prior and likelihood with various sample sizes n and \overline{x} =4



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Plot of $p(\theta|x)$, when n = 1, 10 with $\pi(\theta) \sim N(0, 1)$:

Normal prior and likelihood with various sample sizes n and $\overline{x}=4$



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Normal prior and likelihood with various sample sizes n and \overline{x} =4



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Plot of the $N(0, 10^2)$ prior distribution:

Normal prior



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Plot of $p(\theta|x)$, when n = 1 with $\pi(\theta) \sim N(0, 10^2)$

Normal prior and likelihood with sample size n=1 and \overline{x} =4



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Plot of the $N(0, 0.1^2)$ prior distribution:

Normal prior



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Normal prior and likelihood with various sample sizes n and \overline{x} =4



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Plot of $p(\theta|x)$, when n = 1, 10 with $\pi(\theta) \sim N(0, 0.1^2)$

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The Bayesian approach rocks!

Thomas Bayes



Bayesian Statistical Process Control & Monitoring (Quality Control)

Why Bayesian SPC/M?

- Within the Bayesian approach the unknown parameter(s) θ can be integrated out, deriving the predictive distribution.
- Use of Bayes theorem, updates the (power) prior $\pi(\theta)$ to posterior $p(\theta|\mathbf{X})$ and then for future observable(s) $\mathbf{Y} = X_{n+1}$ we get:

$$f(\mathbf{Y}|\mathbf{X}) = \int f(\mathbf{Y}|\mathbf{\theta}) \ p(\mathbf{\theta}|\mathbf{X}) \ d\mathbf{\theta}$$

- Based on the predictive distribution we will derive two monitoring schemes:
- **PCC:** Predictive Control Charts, for detecting **transient** shifts of large magnitude (outliers).
- **PRC:** Predictive Residual Cusum: for detection of **persistent** shifts of medium/small size (extended to Predictive Ratio Cusum for any distribution in the exponential family).

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Bayesian SPC/M

PCC formulation

- The Predictive Control Chart (PCC) construction will be based on the predictive distribution and it can start as soon as n = 2 and is based on the sequentially updated form of the predictive distribution.
- Precisely, we will determine an IC region, R_{n+1}, where the future observable (X_{n+1}) will most likely be, as long as the process is stable (i.e. no changes occurred).
- The limits of the predictive IC region, R_{n+1} , will be established based on either the overall False Alarm Probability (FAP) or the Average Run Length (ARL).
- Remember that thanks to the (sequentially updated) Bayesian approach, at each time point we test if the process is IC or OOC (i.e. we control the process), but we can also draw inference (i.e. monitor the process), having a Bayes optimal point estimate of the unknown parameter(s).

PCC Illustration and Decision Making



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Bayesian SPC/M

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PCC Illustration and Decision Making



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Bayesian SPC/M

PCC Real Data Application (Medical Lab)

- We will use data that come from the daily Internal Quality Control (IQC) routine of a medical laboratory, monitoring "activated Partial Thromboplastin Time" (aPTT), measured in seconds.
- We gathered 30 daily normal IQC observations (X_i) from a medical lab. Notice that these data are based on control samples and in regular practice will become available sequentially.
- The goal is to accurately detect any transient parameter shift of large size, as this will have an impact on the reported patient results. Thus, it is of major importance to perform on-line monitoring of the process without a phase I exercise.
- We elicit the prior $\pi_0(\theta_1, \theta_2^2 | \tau) \sim NIG(29.6, 1/7, 2, 0.56^2)$ and we had $n_0 = 30$ historical data (from a different reagent).

PCC Real Data Application (Medical Lab)



P. Tsiamyrtzis (Polimi & AUEB)

Bayesian SPC/M

PRC formulation

- In PRC we will guard against informative OOC scenarios, focusing on detecting **persistent** parameter shifts of either parameter of the Normal distribution. Precisely, we developed:
 - **loc-PRC**: Location PRC that aims to identify either upward or downward persistent mean shifts of moderate/small size.
 - sc-PRC: Scale PRC that aims to identify persistent variance increase of moderate/small size.
- Again, thanks to the (sequentially updated) Bayesian approach, at each time point we test if the process is IC or OOC (i.e. we **control** the process), but we can also draw inference (i.e. **monitor** the process), having a Bayes optimal point estimate of the unknown mean and variance parameters.

PRC Real Data Application (Medical Lab)

- We will use hemostasis data that come from the daily Internal Quality Control (IQC) routine of a medical laboratory.
- We are interested in the variable "Factor V", measured in % regarding the international standards in clinical hemostasis, whose deficiencies can induce bleeding disorders of varying severity.
- A change of reagent batch in a lab can introduce a step change to the measurement of Factor V. It is crucial to identify such a change point, especially at the start of the process to avoid impacting clinically the patients care.
- We sequentially gathered 21 normally distributed IQC observations (X_i) from the control samples of a medical lab, where $X_i | (\theta_1, \theta_2^{-2}) \sim N(\theta_1, \theta_2^{-2})$. We choose the parameter $k = \pm 1$ and we tune the PRC in detecting mean step changes, in either upward or downward direction, of one standard deviation size (i.e., $\pm \hat{\theta}_2$).

loc-PRC Real Data Application (Medical Lab)

- We elicit the initial prior $\pi_0\left(\theta_1, \theta_2^{-2} | \boldsymbol{\tau}\right) \sim NIG(31.8, 1/2, 2, 4.41).$
- Furthermore, we have $n_0 = 37$ IC historical data with $\bar{\mathbf{y}} = 31.73$ and $var(\mathbf{y}) = 3.31$. We set $\alpha_0 = 1/37$ to convey the weight of a single data point to these.
- Combining the two sources of information we obtain: $\pi \left(\theta_1, \theta_2^2 | \mathbf{Y}, \alpha_0, \mathbf{\tau}\right) \sim NIG (31.75, 3/2, 5/2, 6.02).$
- We derive the PRC's decision limits h^+ and h^- to achieve FWER = 5% for 21 observations in a two-sided loc-PRC.






























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In Bayesian SPC/M we introduced the **Predictive Control Chart (PCC)** and the **Predictive Residual (Ratio) Cusum (PRC)** mechanisms which:

- they are provided in a general form allowing their use for any **discrete** or **continuous** data from the regular exponential family.
- Any **prior information** and/or **historical data** can be incorporated, boosting performance, but **objective** priors are also available.
- At any stage of the process, apart from **outlier** & **change point** detection, **posterior inference** for the unknown parameter(s) is also available.
- Both PCC and PRC **outperforms** frequentist and Bayesian alternatives and their are found to be **robust** to various misspecifications.

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Bayesian SPC/M: Open Access manuscripts

- Bourazas, K., Kiagias, D., and Tsiamyrtzis, P. (2022). "Predictive Control Charts (PCC): A Bayesian approach in online monitoring of short runs". Journal of Quality Technology, Vol. 54 (4):367–391. https://doi.org/10.1080/00224065.2021.1916413
- Bourazas K., Sobas F. and Tsiamyrtzis, P. (2023). "Predictive ratio CUSUM (PRC): A Bayesian approach in online change point detection of short runs". Journal of Quality Technology, Vol. 55(4):391-403. https://doi.org/10.1080/00224065.2022.2161434 PRC won the 2024 Brumbaugh Award from ASQ which is presented for "the paper making the largest single contribution to the development of industrial application of quality control".
- Bourazas K., Sobas F. and Tsiamyrtzis, P. (2023) "Design and properties of the predictive ratio cusum (PRC) control charts". Journal of Quality Technology, Vol. 55(4):404-421. https://doi.org/10.1080/00224065.2022.2161435

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Questions? Comments? Concerns?